

HEIDENHAIN



Product Information

ECN 1313 EQN 1325

Absolute Rotary Encoders with Tapered Shaft and 01r1 or 07r1 SSI interface

ID 1353127-xx

ID 1353128-xx

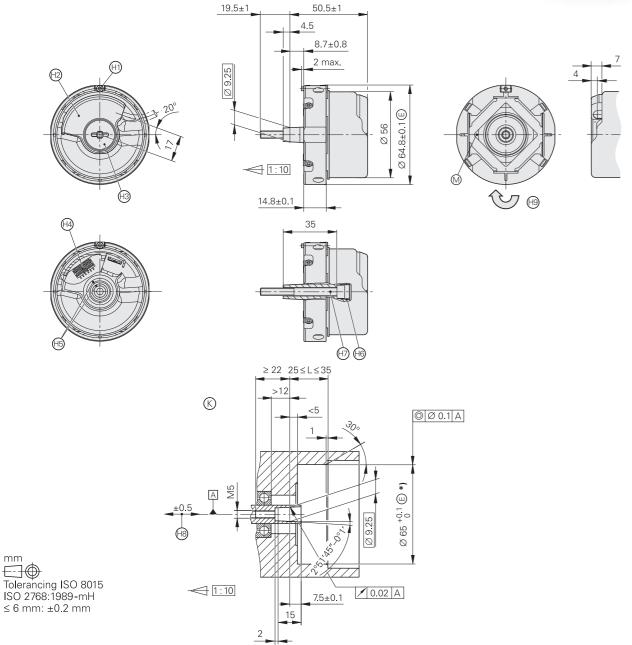
ID 1353130-xx

ECN/EQN 1300 series

Absolute rotary encoders

- 06 stator coupling for axial mounting
- 65B tapered shaft





- © = Required mating dimensions
- Measuring point for operating temperature
 Clamping screw for coupling ring: width A/F 2; tightening torque: 1.25 Nm –0.2 Nm
- 2 = Die-cast cover
- 3 = Screw plug: widths A/F 3 and 4; tightening torque: 5 Nm +0.5 Nm 4 = ECN/EQN: 16-pin PCB connector (12+4)
- 5 = ECN/EQN: zero position of shaft and housing
- 6 = M10 back-off thread
- 7 = Self-locking screw: DIN 6912 M5x50; width A/F 4; tightening torque: 5 Nm +0.5 Nm
- 8 = Compensation of mounting tolerances and thermal expansion; no dynamic movement permitted
 9 = Direction of shaft rotation for ascending position values

	Absolute		
	ECN 1313	EQN 1325	
Interface	SSI		
Ordering designation	SSI01r1	SSI07r1	
Position values per rev.	8192 (13 bits)		
Revolutions	-	4096 (12 bits)	
Electrically permissible speed/ error ²⁾	15000 rpm/±12 LSB		
Calculation time t _{cal}	≤ 5 µs		
Incremental signals	\sim 1 $V_{PP}^{1)}$		
Line count*	512 2048		
Cutoff frequency –3 dB	≥ 500 kHz		
System accuracy	512 lines: ±60"; 2048 lines: ±20"		
Electrical connection	16-pin (12+4) PCB connector		
Supply voltage	4.75 V to 30 V DC		
Power consumption (maximum)	4.75 V: ≤ 600 mW 30 V: ≤ 775 mW	4.75 V: ≤ 675 mW 30 V: ≤ 875 mW	
Current consumption (typical)	5 V: 70 mA (without load)	5 V: 85 mA (without load)	
Shaft	Tapered shaft Ø (9.25 mm); taper: 1:10		
Mech. permiss. shaft speed n	≤ 15000 rpm	≤ 12000 rpm	
Starting torque (typical)	0.01 Nm (at 20 °C)		
Moment of inertia of rotor	$2.6 \cdot 10^{-6} \text{ kgm}^2$		
Natural frequency f _N (typical)	1800 Hz		
Permissible axial motion of measured shaft	±0.5 mm		
Vibration 55 Hz to 2000 Hz Shock 6 ms	\leq 300 m/s ^{2 3)} (EN 60068-2-6) \leq 2000 m/s ² (EN 60068-2-27)		
Operating temperature	-40 °C to 115 °C		
Protection EN 60529	IP40 when mounted		
Mass	≈ 0.25 kg		
ID number	1353127-xx ⁴⁾ 1353128-xx	1353130-xx	

* Please select when ordering

1) More rigorous tolerances 0.8 V_{PP} to 1.2 V_{PP} Signal amplitude:

0.05 Asymmetry: Signal ratio: 0.9 to 1.1 90° ±5° el Phase angle:

2) Speed-dependent deviations between absolute and incremental signals

Speed-dependent deviations between absolute and information signals. Valid as per standard at room temperature; at operating temperatures of up to $100 \, ^{\circ}\text{C}$: $\leq 300 \, \text{m/s}_{2}^{2}$; up to 115 °C: \leq 150 m/s²

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⁴⁾ Encoder with hybrid bearing

Mounting

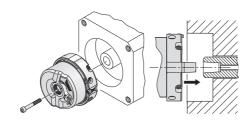
The tapered shaft of the rotary encoder is pressed onto the measured shaft and fastened with a central screw. The stator coupling is clamped by means of an axially tightenable screw in a location hole.

Mounting accessories

Mounting aid

To avoid damage to the cable, use the mounting aid to connect and disconnect the cable assembly. The pulling force must be applied solely to the connector and not to the wires.

For more mounting information and mounting aids, see the Mounting Instructions and the Encoders for Servo Drives brochure. The mounting quality can be inspected with the PWM 21 and ATS software.





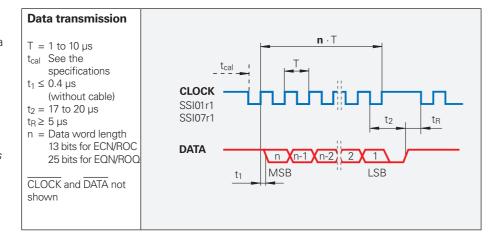
Interface

SSI position values

The **position value** is transmitted, starting with the most significant bit (MSB), over the data lines (DATA) in synchronism with a clock signal (CLOCK) provided by the control. The SSI standard data word length for singleturn encoders is 13 bits, and for multiturn encoders, 25 bits. In addition to the absolute position values, incremental signals can transmitted as well. For a description of the signals, see $1 V_{PP}$ incremental signals in the Rotary Encoders brochure.

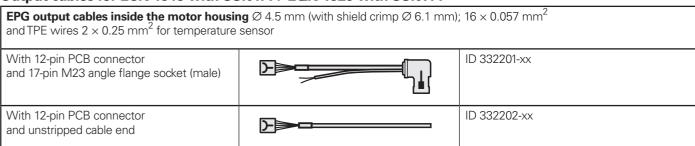
The following **functions** cannot be activated via programming inputs:

- Direction of rotation
- Zero reset (setting to zero)

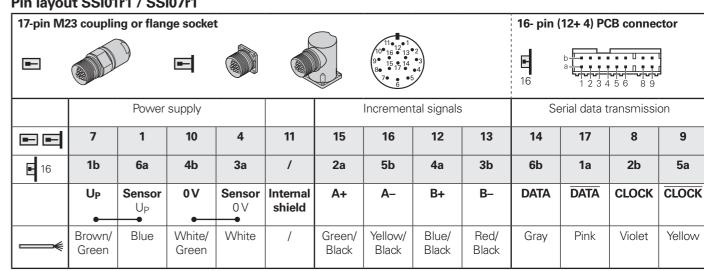


Electrical connection

Output cables for ECN 1313 with SSI01r1 / EQN 1325 with SSI07r1



Pin layout SSI01r1 / SSI07r1



	Other signals	
	5	6
E 16	/	/
	T+ ¹⁾	T - ¹⁾
	Brown ¹⁾	White ¹⁾

Cable shield connected to housing; **U**_P = Power supply voltage; **T** = Temperature **Sensor:** The sense line is connected in the encoder with the corresponding power line. Vacant pins or wires must not be used!

Connections for an external temperature sensor (only for output cables inside the motor, see Temperature measurement in motors); if used, please refer to the information about electromagnetic compatibility in the General electrical information section of the Interfaces of HEIDENHAIN Encoders brochure.

HEIDENHAIN

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This Product Information document supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information document edition valid when the order is placed.



(More information:

Comply with the requirements described in the following documents to ensure correct and intended operation:

208922-xx

1078628-xx

391244-xx

1139530-xx

- Brochure: Encoders for Servo Drives
- Brochure: Cables and Connectors 1206103-xx
- Brochure: Interfaces of HEIDENHAIN Encoders SSI Interface Description
- Mounting Instructions: ECN 1313, EQN 1325, ECN 1325, EQN 1337

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